

# *MATLAB* 教學講義

Advanced Intelligent Robot and  
System Lab, EE, NCKU

# Matlab 基本功能介紹

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Matlab 爲一高品質之數值計算及圖形顯示軟體,其整合了

- 數值分析
- 矩陣運算
- 信號處理
- 圖形顯示

等功能於一體,而提供了各種工程分析與設計之能力.

Reference Book : Matlab 程式設計與應用 張智星 清蔚科技  
MATLAB 6.X 與基礎自動控制 松崗出版社

# Matlab 基本設計

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- 直接在 **command window** 下一行行執行的 **Script M-file**
  - 所需的變數直接從 **workspace** 中去獲得並建立
  - 不需輸入輸出引述的呼叫
  - 無法保留
- 可存取的 **M file**
  - 開啓方法
    - **File -> New -> M-file**
    - **New M-file**
  - 以 **Editor/Debugger** 撰寫程式

# Command window instruction

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- 多項式之表示法及運算：

MATLAB使用列向量(row vector)來表示一個多項式,例如：  
如： $p(x) = x^3 - 2x + 5$  表示為  $\mathbf{p} = [1 \ 0 \ -2 \ 5]$ ;

- 指令roots： $\mathbf{r} = \text{roots}(\mathbf{p})$

```
r = -2.0946  
    1.0473+1.1359i  
    1.0473 -1.1359i
```

- 指令poly： $\mathbf{p1} = \text{poly}(\mathbf{r})$

```
p1= 1.0000    0.0000   -2.0000    5.0000
```

# Command window instruction

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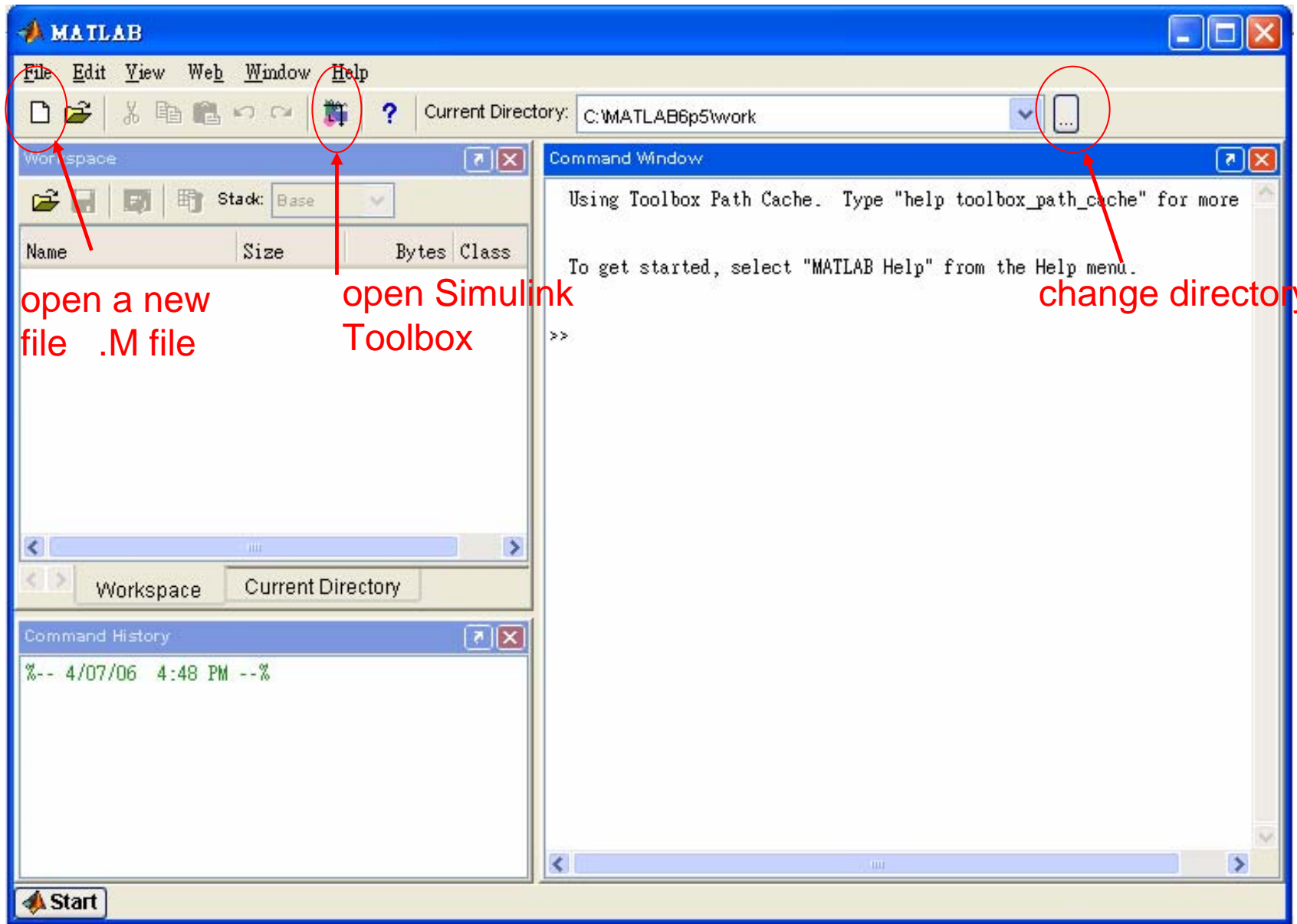
- inv指令

```
A= [1 2 3 ; 4 5 6 ; 7 8 0];
```

```
inv(A)
```

```
ans =
```

```
-1.7778  0.8889 -0.1111  
 1.5556 -0.7778  0.2222  
-0.1111  0.2222 -0.1111
```



open a new  
file .M file

open Simulink  
Toolbox

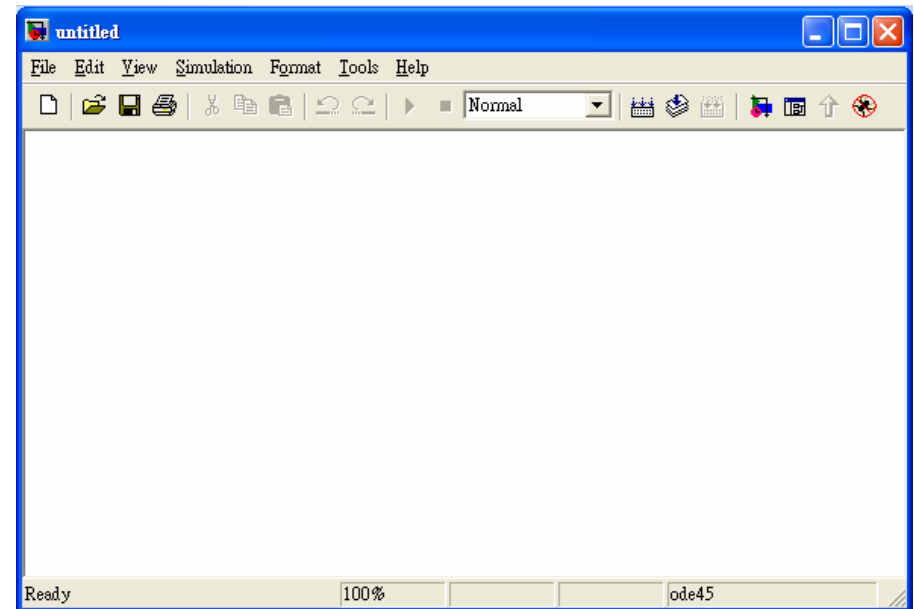
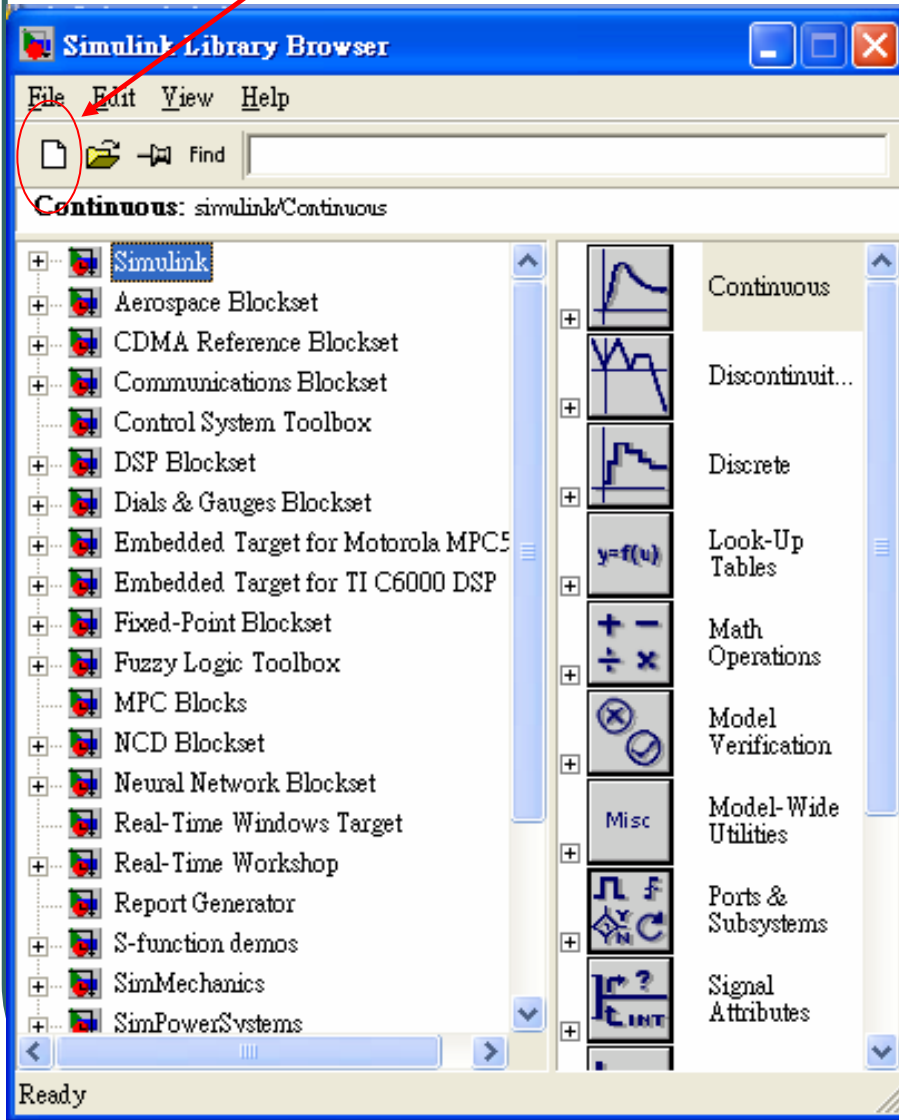
change directory

# Simulink Tutorial

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- **SIMULINK 設計**
  - 在 **matlab** 環境下的模擬工具, 檔案類型為 **.mdl** 檔
  - 提供圖形化的功能方塊, 建構模擬系統
  - 可加入 **C**, **FORTRAN** 語言, 並依據 **S-function** 的標準格式, 建立自行定義的功能方塊
  - 執行方法
    - **Command window** 下直接鍵入 **simulink**
    - **New simulink model**
    - **File -> New -> Model**

Create a new model





# SIMULINK Library-1

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## continunous

$$\frac{1}{s}$$

Integrator

$$\begin{aligned} \dot{x} &= Ax + Bu \\ y &= Cx + Du \end{aligned}$$

State-Space

$$\frac{1}{s+1}$$

Transfer Fcn



Transport Delay

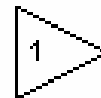


Variable Transport Delay

$$\frac{(s-1)}{s(s+1)}$$

Zero-Pole

## Math operations



Gain



Sum

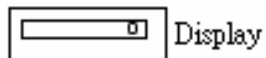


Product

# SIMULINK Library-2

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## sinks



Display



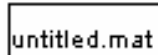
Floating Scope



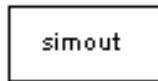
Out1



Scope



To File



To Workspace



XY Graph

## source



In1



Pulse Generator



Ramp



Random Number



Repeating Sequence



Signal Generator



Signal Builder



Sine Wave



Step

# EX.1

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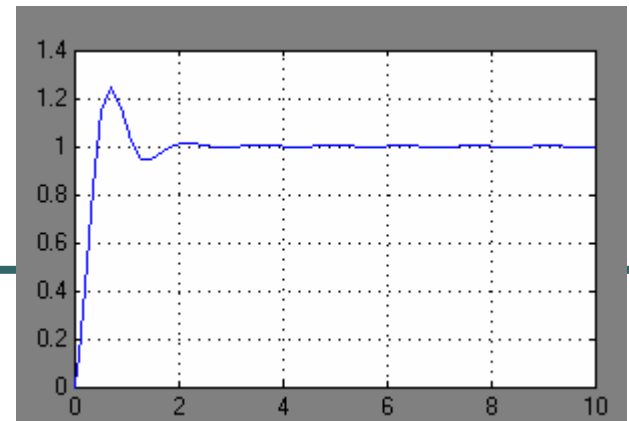
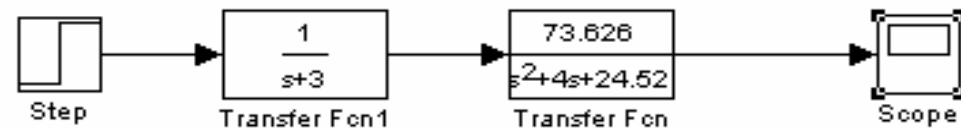
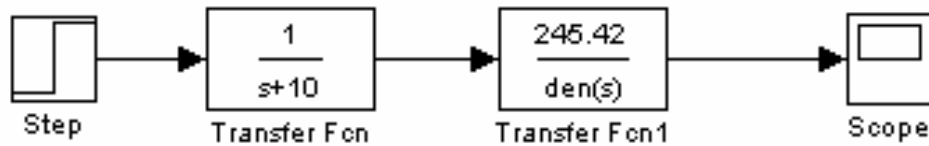
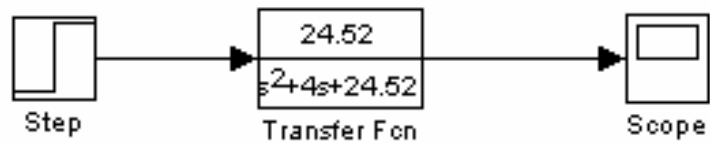
- Using SIMULINK to compare response of three-pole systems

$$T_1(s) = \frac{24.542}{s^2 + 4s + 24.542}$$

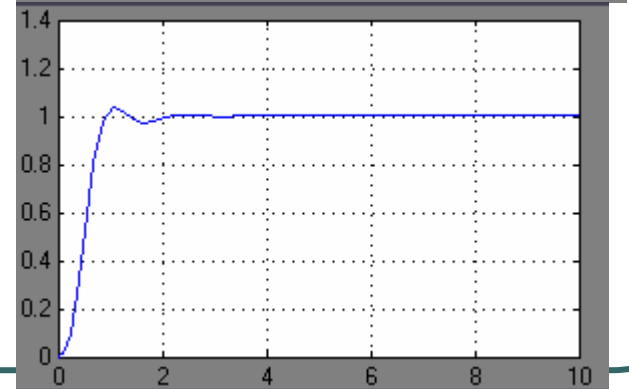
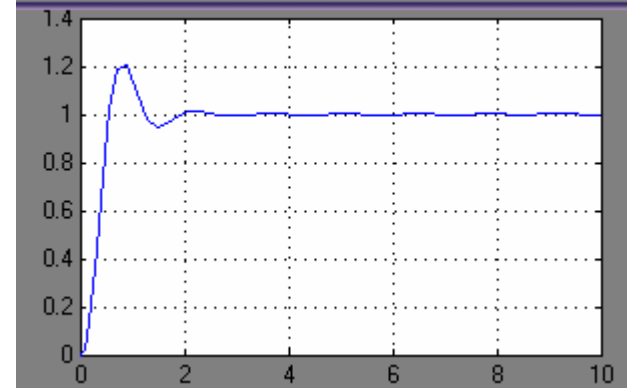
$$T_2(s) = \frac{245.42}{(s + 10)(s^2 + 4s + 24.542)}$$

$$T_3(s) = \frac{73.626}{(s + 3)(s^2 + 4s + 24.542)}$$

# Sol.

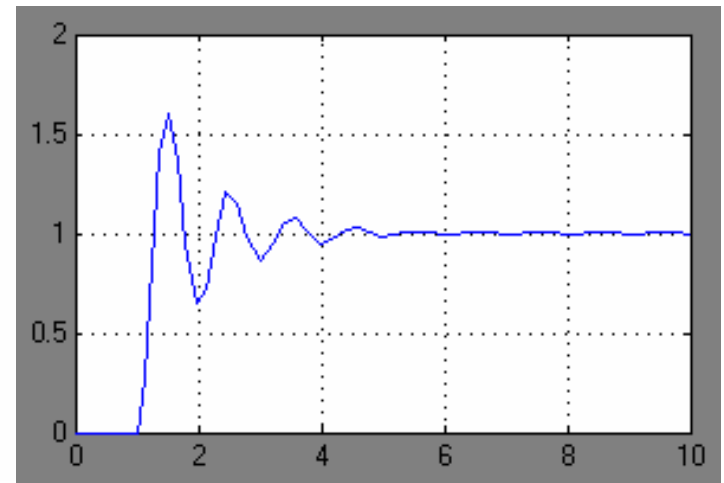
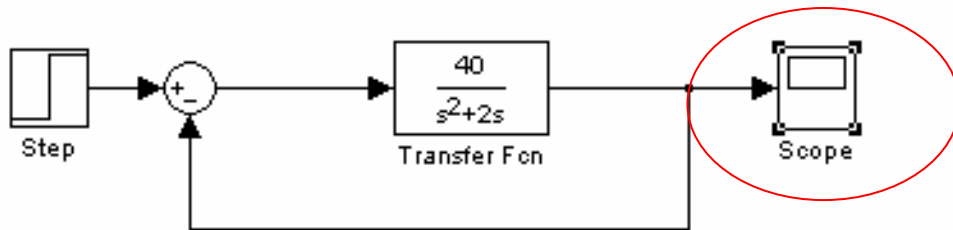


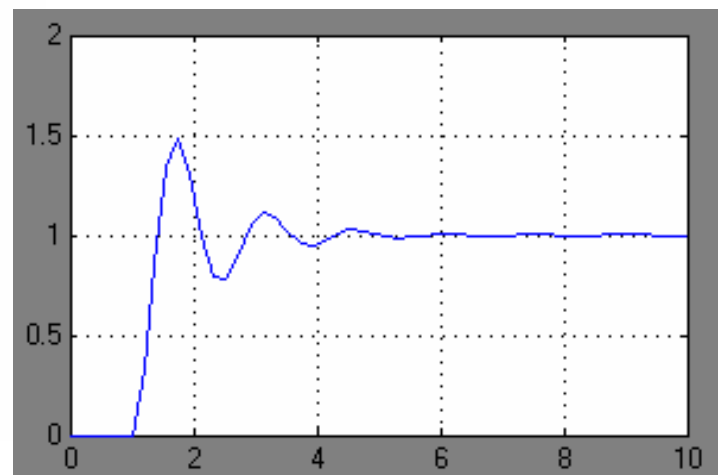
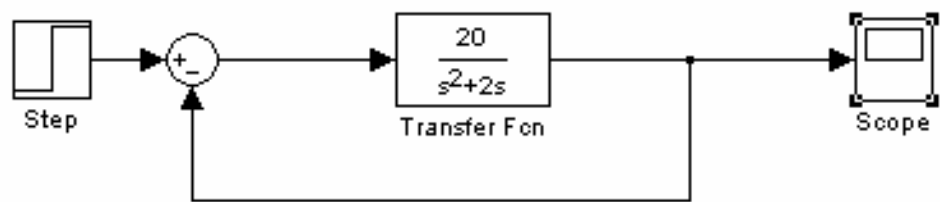
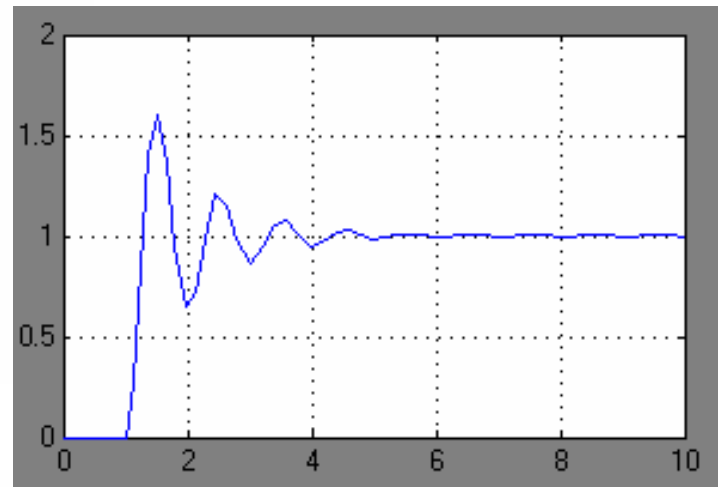
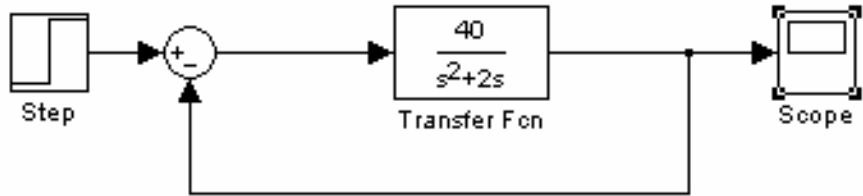
Time offset: 0

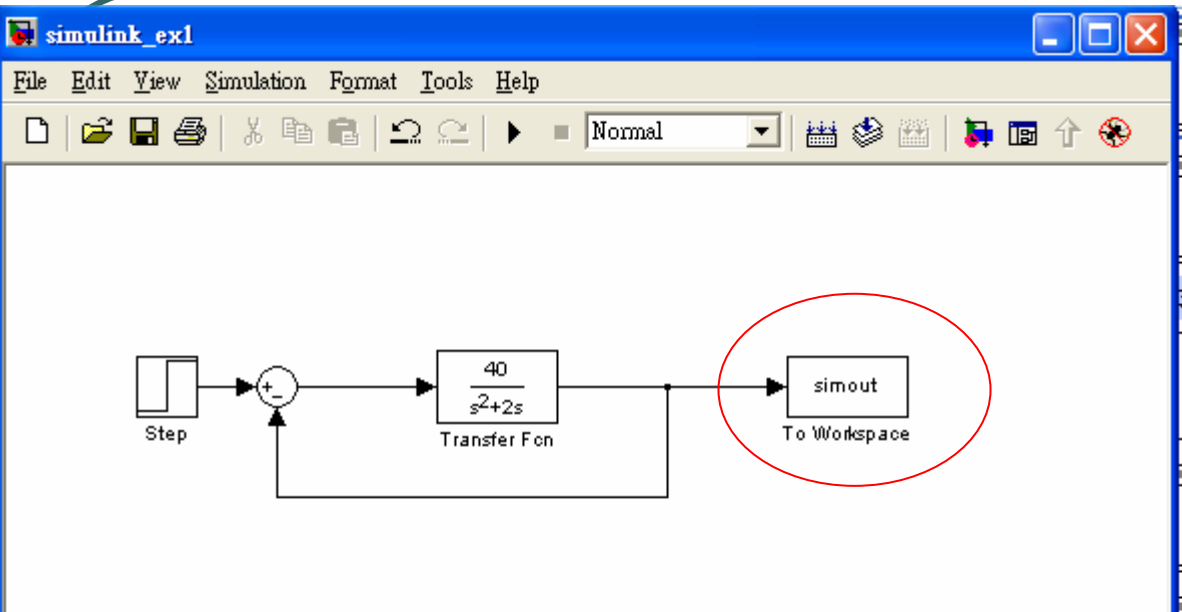


# EX.2

- 以Simulink模擬  $\frac{Y(s)}{X(s)} = \frac{G(s)}{1+G(s)}$  ，其中  $G(s) = \frac{40}{s^2 + 2s}$







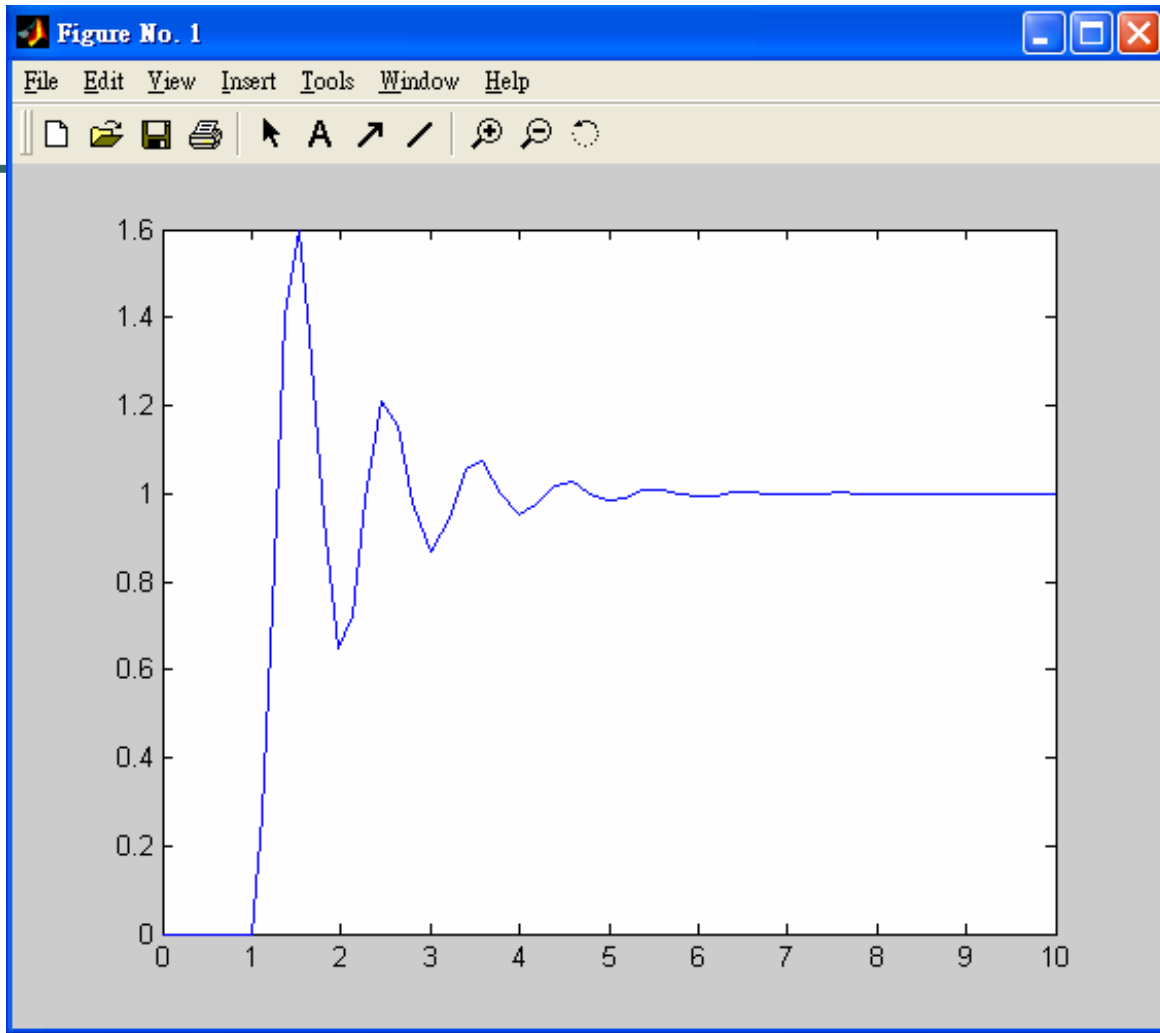
The MATLAB interface displays the following information:

**Workspace**

Name	Size	Bytes	Class
simout	57x1	456	double
tout	57x1	456	double

**Command Window**

```
Using Toolbox Path Cache. Type "help toolbox_path_cache" for more  
  
To get started, select "MATLAB Help" from the Help menu.  
  
>> plot(tout,simout)  
>> |
```





# HOMEWORK 1

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- (1)  $G(s) = \frac{as+4}{s^2+2s+4}$   $a=0,1,2$ ，試以simulink探討步階響應變化(畫在同一個圖上)
- (2)  $G(s) = \frac{s+20}{(s+2)^2(s+5)}$  試求脈衝及步階響應
- (3) 輸入系統延遲的轉移函數為  $G(s) = \frac{3e^{-0.25s}}{s+3}$   
試以simulink畫出步階響應圖